# Development of a Two-way Nested LETKF System for Cloud Resolving Model

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- Almost every years, heavy rainfalls of Baiu fronts and typhoons cause floods and landslides in Japan.
- Predictions of these phenomena are relatively easier because these rainfalls are caused by large scale convergence or topography.



- Besides Baiu fronts and typhoons, local heavy rainfall and tornados cause disasters.
- Predictions of these phenomena are difficult because they are generated in weak convergence. Accuracy of their forecasts should be improved (Data assimilation. Probabilistic forecast)
- → Cloud resolving two way nested LETKF system.

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- To reproduce local heavy rainfalls, mesoscale environment and convection cells should be reproduced simultaneously by the numerical models with large and small grid intervals.



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#### Field Experiments (TOMACS)

A field campaign in the Tokyo metropolitan area with a dense observation network is being performed by MRI and thirteen groups in the summers of 2011–2013.



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- LETKF (Local Ensemble Transform Kalman Filter; Miyoshi and Aranami, 2006) was used in this study. To reflect the results of the inner LETKF in the outer model, a two-way nested system has been developed.

## Necessity of a nested assimilation system

- •Thunderstorm occurred on 31<sup>st</sup> July 2007, which was one of targets of B08RDP Tier2 experiments was reproduced by NHM.
- Rainfall system extending north-south direction passed Beijing City and 3-hour rainfall of 70 mm was observed there.
- •Rainfall intensity and rainfall amount were reproduced by the NHM with grid interval of 2km (Tier2). Initial and boundary conditions of Tier-2 were produced from the output of the NHM with grid interval of 15km (Tier-1).
- •Rainfall intensity and rainfall amount with the grid interval of 15km were produced from outputs of 2km, and compared with the results of Tier1.





- Except P02, rainfall amounts of Tier-1(15km) were larger than those of Tier-2(km).
- •Maximum of rainfalls of Tier-2(2km) was larger than those of Tier-1(15km).
- •Grid numbers where rainfall exceeds1.0mm of Tier-1(15km) were wider those of Tier-2(2km).
- •Histogram indicates that rainfall was more concentrated in Tier-2(2km).
- •Rainfall amounts and intensities of Tier-2 (2km) can not be simply estimated from those of Tier-1(15km).





- There was a high temperature area at Osaka and a thermodynamic low system was generated here.
- A northeasterly flow and a southerly flow were converged at Osaka Plain.

### Airflow Structure of heavy rainfall



(Left) Horizontal wind at 1520JST obtained by Dual analysis from Osaka and Kanku radar data. (Right) Vertical wind distribution at 1520JST.

### **Results of Single LETKF (5km-NHM)**



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#### Experiments with changing amplitudes of deviations



#### Reason why thunderstorm was not reproduced



Position of thunderstorm was not reproduced by changing deviation amplitude.

More assimilation data is needed

### NHM-3DVar (JNoVA0) (Miyoshi ,2003,Seko 2008)

## Assimilation of Radial wind data



LETKF Grid interval is too coarse ⇒updraft is weak





Increment of surface temperature and horizontal wind

When Doppler radar data was assimilated, initial convergence was intensified.

### Assimilation of Radial wind data





### Forecast from assimilated fields (17JST)



## Forecast from assimilated fields (17JST)





Meteorological Agency. Assimilation window was 6 hours.





Assimilation window was 1 hour.



• Initial boundaries of the inner LETKFs were produced from forecasts of the outer LETKF.









## Results of nested LETKF system



## Low-level convergence of water vapor

- To improve convergence of **water vapor**, we want to assimilate the precipitable water vapor (PWV) and horizontal wind data .
- PWV can be obtained from delays of signals from GNSS.
   GNSS Satellite



## How to estimate PWV data

- A GPS network (GEONET) has been established in Japan.
- Horizontal distances of GPS receivers are about 25 km.
- GEONET provides high resolution data of PWV that can express the environments of local heavy rainfalls.



## How to estimate PWV data



- Signals from GNSS satellites are delayed by water vapor in the atmosphere. Delay along the path between GNSS satellites and receivers is called the Slant Total Delay (STD).
- The Zenith Total Delay (ZTD) is estimated from the STDs by multiplying the mapping function of the elevation angles.
- The Precipitable Water Vapor (PWV, vertically integrated amount of water vapor) is estimated from the ZTDs.

## Accuracy of GPS-PWV data observed by GEONET

Comparison with GPS-PWV and sonde-PWV (Period Jun. 1999 ~ May 2000). Distances between GPS-PWV and sonde-PWV were less than 10km horizontally and 20m vertically.

	GPS点	水平距離	高度差
		(km)	<u>(m)</u>
47420/根室	0006	7.5	-6.0
47580/三沢	0539	2.7	11.3
47590/仙台	0037	7.3	-11.3
47600/輪島	0053	1.0	0.1
47646/舘野	0584	6.6	0.0
47681/浜松	3050	9.8	-6.8
47744/米子	0654	1.0	3.9
47918/石垣島	0750	0.9	12.5
47945/南大東島	0497	0.6	1.2
*高度差=GPS点標高-高層観測点標高			

#### **RMS = 2.3mm** (Precise orbit was used in the

estimation of GPS-PWV.)



### **Observed GPS-PWV**

2008 / 09 / 05 / 05 00(UTC)

GPS PWV site = 1158

FLUX\_DIV



## Assimilation method GPS-PWV

**Observation data : GPS-derived PWV** 

Difference between the GPS receivers' altitude and model topography <50 m.

First guess and statistical value obtained by NHM-LETKF

Vertical profiles of T, RH and the spread of RH within the range of ±15 km from GPS receivers. <u>RH profiles were produced.</u> (Input data of LETKF)

Thinning of the vertical layer in the profiles was performed, because of the vertical correlation of the observation error.



Assumption: the difference between analysis and first guess is larger at the layer with a wider spread of RH.

Water vapor was should be modifies only at the layer of which the correlation with PWV was large.

7 Input RH data of the LETKF was produced by increasing of average of first guess value in proportion to maximum spared of RH at layers, of which the correlation with PWV was large.



## Assimilation of GPS-PWV data





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## Assimilation of GPS-PWV data





### GPS-slant water vapor (SWV) data

- •Slant water vapor (SWV) was the water vapor amount along the path from GPS satellite and GPS receivers
- SWV was retrieved from PWV, gradient and residual, and surface meteorological data, such as T and P.
- •SWV was assimilated by using the same method of PWV, except the paths were slanted.



## Assimilation of GPS-SWV data





### Horizontal wind obtained from Doppler radars



#### Horizontal wind improves the rainfall forecasts, although the impact was weaker than GPS-PWV.



#### Both GPS-PWV and horizontal wind were assimilated simultaneously, number of the improved member were increased.



Blue and pink circles indicate the rainfalls improved by GPS and radar data

#### **Radial winds of Doppler radar also improve** the rainfall forecasts.





#### Both GPS-PWV and radial wind were assimilated simultaneously, the number of the improved members were increased.



Blue and pink circles indicate the rainfalls improved by GPS and radar data



Spreads of with nest and w/o nest were compared.



- Nesting increased the spread slightly in this case.
- Influence expanded into outer regions (pressure).
- More case studies are needed to obtain the conclusion.

Multi inner LETKFs experiment



Four inner LETKFs were deployed in the outer LETKF.

- Weight was determined from the distance from the boundary of Inner LETKF.
- Inner LETKFs are not necessarily deployed next to each other. (example. deployed at each radar sites)

### **Overlap regions of patches (Boundary Problem )**



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- Four inner LETKFs were deployed in the outer LETKF.
- Unrealistic convection cells were not generated on the boundary.

### Further improvements





Rainfall region near the boundary was intensified. Regions near the boundary were modified by no-cost smoother.





#### Spread of 11JST (2 cycles of Inner LETKF, 2km)



Large spread area in  $\overline{L}$  corresponds to mountain ranges. S different from  $\overline{L}$ . S should be used because it contains *small scale perturbations*.

### Further improvements



# **Summary and future plan**

- 1. The nested LETKF system is under development to reproduce the environments and convection cells.
- 2. The Sakai intense rainfall on 5<sup>th</sup> Sep. 2008 was reproduced by the nested LETKF system.
- **3.** GPS-water vapor data and the radial winds of the radar data increased the number of forecasts in which the thunderstorm was reproduced.
- 4. The number of kinds of assimilation data will be increased. Other improvements on the nested system will be implemented.

## Tornado Occurred on 6<sup>th</sup> May 2012



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### Downscale Experiments with $\Delta x=350m$



Positions and durations depend on the ensemble members.
Tornados occurred in three areas, which were the same as the observations though they were shifted northward by 10 km.



From 1130JST to 1430JST

#004: Intense vortex is maintained. #007: Intense vortex isn't generated.







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# Thank you for your attention



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